[illegible] **PY-LP400** [illegible] [illegible] [illegible] [illegible] [illegible] [illegible]

[illegible]:

[illegible] [illegible]	3000 [illegible]
[illegible]-[illegible] [illegible]	100,000
[illegible] [illegible]	ZEM510
[illegible]	[illegible] [illegible]
[illegible] [illegible]	[illegible] v10.0
[illegible]	RS232 / 485, [illegible] / [illegible]
[illegible] [illegible]	Workcode, [illegible], DLST, [illegible]-[illegible], [illegible] [illegible] [illegible], [illegible] [illegible] [illegible]
[illegible] [illegible]	[illegible] / Mifare, [illegible] [illegible]
[illegible]	3 [illegible] [illegible] [illegible]
[illegible] [illegible] [illegible]	5V [illegible] 2A
[illegible] [illegible]	0-45
[illegible] [illegible]	20% -80%
[illegible]	200X145X58 [illegible]
[illegible] [illegible]	1.05 [illegible]

OEM [illegible]	[illegible]
[illegible]	[illegible]
[illegible] [illegible]	[illegible]
[illegible] [illegible] [illegible] [illegible]	[illegible]
[illegible] [illegible] [illegible] [illegible]	[illegible] [illegible]

[illegible]: [illegible], [illegible], [illegible], [illegible], [illegible], [illegible] [illegible] [illegible]